





## **MAIN FEATURES**

Cost effective encoder for asynchronous motors, suitable for elevators and stage machinery.

- · 3 channel encoder (A / B / Z) up to 2500 ppr
- · Power supply up to +28 V DC with several electrical interfaces available
- · Up to 105 kHz output frequency
- · Cable output, connectors available on cable end
- · Sturdy mechanic
- · Up to 40 mm bore diameter
- · Shaft fixing by collar clamping

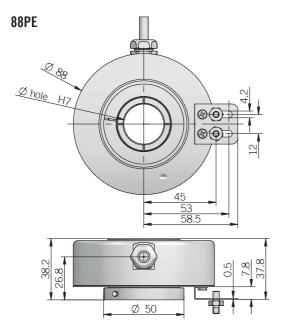




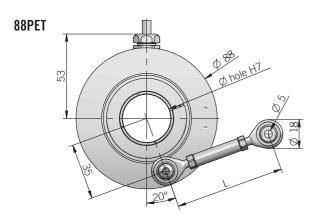
ORDERING CODE	EH	88PE	1024	S	5/28	P	30	X	3	PR	. XXX
	SERIES										
incremen	ital encoder series EH										
through hollows	shaft with torque stop s	MODEL Int 88PF									
through hollow sl	haft for torque arm fixin e refer to Accessories for to	g 88PET									
picco		RES	OLUTION								
	ppr refer to the	r from 500 vavailable i									
	Total to the		ZER	RO PULSE							
		W	ithout zer/ with zer	o pulse S o pulse Z							
				POWER	SUPPLY						
		(with	n L electrica	al interface) 5 28 V	5 V DC 5 DC 5/28						
					TRICAL IN						
						sh-pull P e driver L					
		powe	er supply 5	5/28 V DC -		S-422 RS					
						BORE D	IAMETER mm 25				
						/ 1.00	mm 30				
						(mod. Pl	E) mm 35 E) mm 38				
							E) mm 40 I <b>nclosur</b>	r DATING			
							NGLUSUK	IP 54 X			
							MA	X ROTATIO			
								30	00 rpm 3 <b>OUTP</b>	UT TYPE	
			nroformad -	علم المعردا	. 1 5 / 0 / 0	/ E / 10		able (stand	ard length (	0,5 m) PR	
			ргетеггеа с	avie iength	5 1,5 / 2 / 3	/ 5 / 10 M,	to be added	after OUTP	JI ITPE (eg.		VARIANT

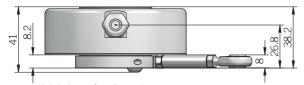
custom version XXX





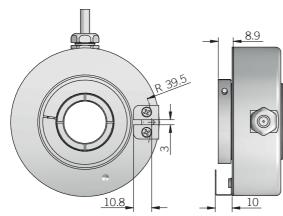
for torque pin please refer to Accessories





torque arm not included, please refer to Accessories

OPTIONAL TORQUE STOP SLOT



for torque stop slot and torque pin please refer to Accessories

recommended mating shaft tolerance g6 dimensions in mm

ELECTRICAL SPECIFICATIONS				
Resolution	from 500 to 2500 ppr			
Power supply <sup>1</sup>	$5 = 4,5 \dots 5,5 \text{ V DC}$ $5/28 = 4,5 \dots 30 \text{ V DC}$ (reverse polarity protection)			
Power draw without load	800 mW			
Max load current	20 mA / channel			
Electrical interface <sup>2</sup>	push-pull / line driver HTL (AEIC-7272 or similar) line driver RS-422 (AELT-5000 or similar)			
Max output frequency	105 kHz			
Counting direction	A leads B clockwise (shaft view)			
Index signal	90°e (gated A&B)			
Mean time to dangerous failure (MTTF <sub>d</sub> ) <sup>3</sup> according to EN ISO 13849-1	220 years			
Mission time (Tm) <sup>3</sup>	20 years			
Diagnostic coverage (DC) <sup>3</sup>	0%			
Cable type	shielded - fixed installation conductors section 0,22 mm²/AWG 24 bending radius min 60 mm			
Electromagnetic compatibility	according to 2014/30/EU directive			

**RoHS** | according to 2011/65/EU directive

**UL / CSA** file n. E212495

MECHANICAL SPECIFICATIONS			
Bore diameter	ø 25 / 30 / 35 / 38 / 40 mm		
Enclosure rating	IP 54 (IEC 60529)		
Max rotation speed	3000 rpm		
Shock	50 G, 11 ms (IEC 60068-2-27)		
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)		
Moment of inertia	45 x 10 <sup>-6</sup> kgm <sup>2</sup> (10,68 x 10 <sup>-4</sup> lbft <sup>2</sup> )		
Starting torque (at +20°C / +68°F)	< 0,02 Nm (2,83 Ozin)		
Bearing stage material	aluminum		
Shaft material	up to ø 38 mm aluminum ø 40 mm stainless steel		
Housing material	aluminum		
Bearings	n.2 ball bearings		
Bearings life	10 <sup>9</sup> revolutions		
Operating temperature <sup>4, 5</sup>	-30° +85°C (-22° +185°F)		
Storage temperature <sup>5</sup>	-30° +85°C (-22° +185°F)		
Weight	350 g (12,35 oz)		

as measured at the transducer without cable influences

<sup>&</sup>lt;sup>5</sup> condensation not allowed

CONNECTIONS		
Function	Cable P	Cable L/RS
+V DC	red	red
0 V	black	black
A+	green	green
A-	/	brown or grey
B+	yellow	yellow
B-	1	orange
Z+	blue	blue
Z-	1	white
÷	shield	shield

## **RESOLUTIONS**

500 - 512 - 720 - **1000** - **1024** - 1440 - 2500

please directly contact our offices for other pulses, preferred resolutions in bold





 $<sup>^{\</sup>rm 2}$  for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

 $<sup>^{\</sup>rm 3}$  this product is not a safety component, for further details refer to TECHNICAL BASICS section

 $<sup>^{\</sup>rm 4}$  measured on the transducer flange