



#### MAIN CHARACTERISTICS

EMSSS is an absolute linear magnetostrictive transducer with SSI output.

Main characteristics of magnetostrictive transducer is the absence of electric contact on the enclosure so there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.

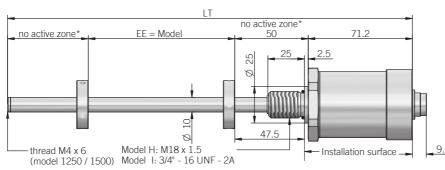
This series has been designed for being mounted internally to high preassure (350 bar, 500 bar peak) such as hydraulic or pneumatic cylinders.



ORDERING CODE	EMSSS	500	S	24	G	Н	10	R5	P	A
	SERIES SERIES									
	linear magnetostrictive transducer with SSI output EMSSS	STROKE								
	mm from 100	to 1500								
	see table for stroke a E		E RATING							
			IP 67 S							
		(F	M357) 21	<b>LENGTH</b> +1 bit 21						
				24 bit 24 25 bit 25						
					DE TYPE					
					binary B gray G					
					THRI	EAD TYPE				
					M1 3/4" -	.8 x 1,5 H .16 UNF I				
					DISPLACEMENT SPEED					
				max speed 10 m/s 10   RESOLUTION						
							0,00	5 mm R5 mm R10		
							0,020	mm R20		
							0,040	mm R40	UT TYPE	
						DIN 4	cable (st	andard leng	th 1 m) P	
						DIN 4	5322 M16	6 pin conn <b>n</b>	ector C6   <b>UTPUT DIR</b>	FCTION
								U	טווע וט ווט	axial A

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## **EMSSS**



 $^{\star} = 55$  mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole

dimensions in mm

- $\cdot~$  OR 15,4 x 2,1 (mod.H) / OR 16,36 x 2,21 (mod.I) included
- · Cursors and socket connector not included, please refer to Accessories

ELECTRICAL SPECIFICATIONS					
Resolution	5 - 10 - 20 - 40 μm				
Indipendent linearity	≤ ± 0,02 % FS (min ± 0,060 mm)				
Repeatability	< 0,01 mm				
Hysteresis	≤ ± 0,005 % FS (min 0,010 mm)				
Sampling time	1 ms (mod. 100 1000) 2 ms (mod. 1250 1500)				
Power supply <sup>1</sup>	10 32 V DC				
Power ripple   1 Vpp max					
Max load current	50 mA max				
Electrical interface	RS-422				
SSI output code	binary or gray				
Clock frequency	50 kHz 1 MHz				
SSI monostable time (Tm)	16 μs				
SSI frame	21 / 24 / 25 bit data length				
Counting direction	increase				
Protection against overvoltage	yes				
Protection against polarity inversion	yes				
Self-resetting internal fuse	yes				
Electrical insulation	500 V DC (+V DC / earth)				
Cable type	twisted pair shielded - fixed installation conductors section 0,22 mm²/AWG 24 bending radius min 75 mm				
Electromagnetic compatibility	according to 2014/30/EU directive				
RoHS	according to 2011/65/EU directive				

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CONNECTIONS						
Function	Cable P	6 pin M16 C6				
+ V DC	blue / white	5				
0 V	blue	6				
DATA +	brown / white	2				
DATA -	orange	1				
CLOCK +	green / white	3				
CLOCK -	green	4				

MECHANICAL SPECIFICATIONS					
Stroke	100 - 150 - 200 - 300 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1250 - 1500 mm				
Electric stroke (EE)	see model (mm)				
Overall dimensions (LT)	EE + 176,2 mm (mod. 100 1000) EE + 181,2 mm (mod. 1250 1500)				
Enclosure rating	IP 67 (IEC 60529)				
Detected measurement	displacement				
Travel speed	10 m/s max				
Acceleration	100 m/s <sup>2</sup> max				
Speed measurament range	min 0 0,1 m/s max 0 10 m/s				
Speed accuracy	< 2 %				
Shock	100 G, 11 ms, single shock (IEC 60068-2-27)				
Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)				
Rod / housing material	1.4401 / AISI 316 stainless steel				
Operative pressure	500 bar				
Cursor type	floating cursor				
Temperature coefficient	20 ppm FS / °C				
Operating temperature <sup>2, 3</sup>	-30° +90°C (-22° +194°F)				
Storage temperature <sup>3</sup>	-40° +100°C (-40° +212°F)				

<sup>&</sup>lt;sup>1</sup> as measured at the transducer without cable influences

C6 connector (6 pin) DIN 45322 front view



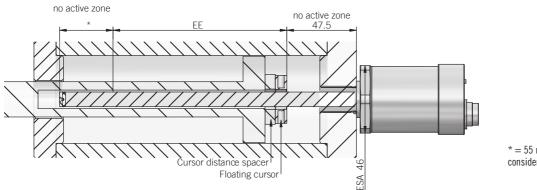




<sup>&</sup>lt;sup>3</sup> measured on transducer

<sup>&</sup>lt;sup>4</sup> condensation not allowed

## **INSTALLATION EXAMPLE**



\* = 55 mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole

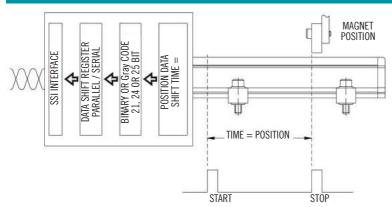
For the correct installation of rod-type magnetostrictive transducers in hydraulic cylinders, remember that the cylinder head must be made of non-magnetic material where the threaded hole will be drilled to install the transducer. If not, the residual magnetisation caused by drilling the threaded hole must be less than 4 Gauss. Sealing surface must be free from scratches longitudinal or spiral

Ro 1,6  $\mu m$  for sealing with non pulsating pressure Ro 0,8 µm for seals with pulsating pressure

Suggested o-ring (model H) Parker 6-349 15,4 x 2,1 Material: Viton 90° Shore A Mixes: Parker N552-90

Suggested o-ring (model I) Parker 3-908 16,36 x 2,21 Material: Viton 90° Shore A Mixes: Parker N552-90

#### SSI BLOCK DIAGRAM



SSI output goes to 0 if the echo is absent (magnet out of measurement range or internal device error)

SSI CABLE LENGTH									
Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m				
Baud rate	1 Mbaud	400 kbaud	300 kbaud	200 kbaud	100 kbaud				

# **INSTALLATION NOTES**

The transducer must be installed away from sources of magnetic fields, both static and 50 Hz (electric motors, solenoids, etc.).

- $\cdot$  with floating cursor assembly support must be made with nonmagnetic material
- · the transducer connection cable must be wired separate from power cables and/or solenoid controls, drives, or remote switches
- power supply must be drawn from dedicated power supply and connected directly to power terminals as near as possible
- since the transducer cursor is a magnet, make sure there are no iron filings or small fragments of magnetic metal near the transducer. This could produce an accumulation of material on the cursor, with consequent sliding problems
- · cable shield must be connected on both sides (PLC and transducer)
- · if the transducer is installed in a cylinder isolated from the ground, the cable shielding on PLC side must be grounded.

